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that is concerned predominantly with mechanics has a brief section devoted to computational considerations. This book evolved from class notes used to teach "Introduction to Robotics" at Stanford University during the autunms of 1983 through 1985. The first and second editions have been used at many institutions from 1986 through 2002. The third

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Robot Mechanics and Control, Part I | edX

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INTRODUCTION TO ROBOTICS

Introduction to Robotics: Mechanics and Control (Buy Online) is written by John J. Craig, and this book stands as one of the most popular university textbooks on robotics. This textbook has a long history with the first edition being published in 1986, and the fourth edition was released in 2017 with all new material to keep pace with the rapidly evolving field of robotics.

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Over all, I would say this is the best source for understanding mechanics and control theory as it relates to robotics motion. It really gets into the details that books on the subject of computational robots such as "Introduction to Autonomous Mobile Robots" and "Computational Principles of Mobile Robotics" simply do not have the room to accommodate.

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